

# AN11737

## Handling information for sensors in SOT453 and SOT477 packages

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Application note

### Document information

Info	Content
<b>Keywords</b>	SOT453, SOT477, package, sensor, assembly
<b>Abstract</b>	This document describes the limitations to package handling and precautions for safe assembly of speed sensors in SOT453 and SOT477 packages.



## Revision history

Rev	Date	Description
1	20151130	initial version

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## 1. Introduction

### 1.1 General

NXP Semiconductors is not the owner of customer processes and cannot test them under all conditions. Therefore, the information below is a general guideline for product handling and package assembly.

It does not replace the process development and release by the customer.

### 1.2 Package information

The products have two (SOT453) or three (SOT477) leads. All products contain a magnet attached to the plastic body in different size, depending on the application.

Most products have a nickel finish plating, which is preferred for welding and crimping. Some have a tin finish plating to ensure good soldering performance. All products are recommended for thermoplastic overmolding. The leads can be bent according to customer requirements.

The products require gentle handling as especially the leads can bend unintentionally due to their small cross section and length.

The material of the attached ferrites is brittle, so collision with other hard materials should be avoided to prevent chipping.

The magnets attract ferromagnetic materials as well as other magnets with the risk of hard contacts. The magnets may collect tiny ferromagnetic or magnetic particles.

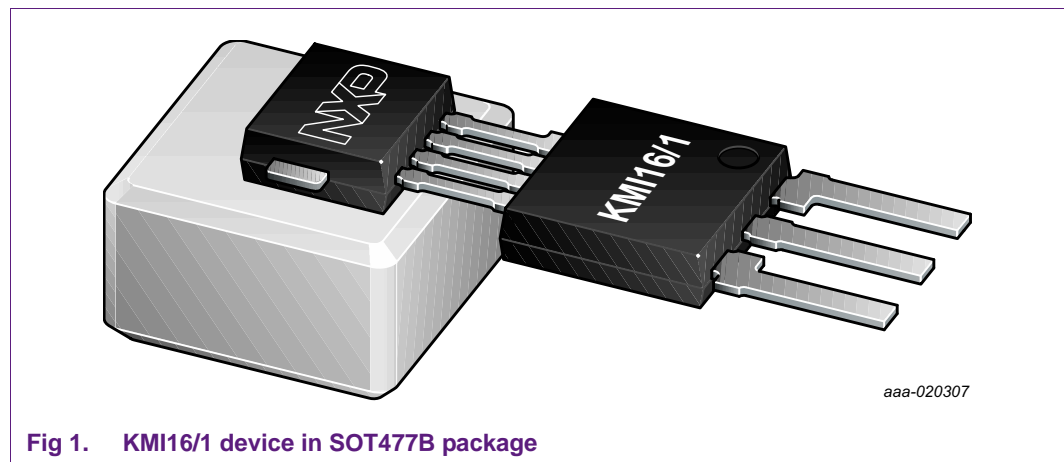
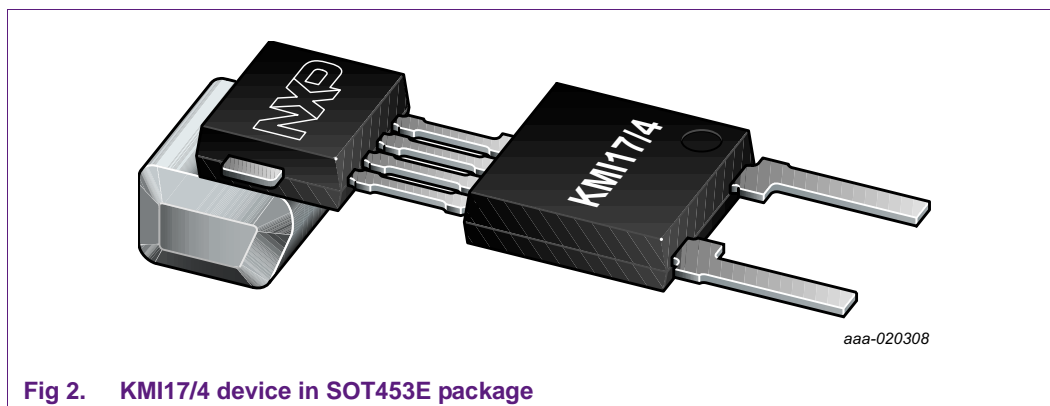


Fig 1. KMI16/1 device in SOT477B package



## 2. Storage

### 2.1 Store conditions

Secure and clean store areas must be provided to isolate and protect the products.

Conditions in the store areas shall be such that the quality of the products does not deteriorate due to, among others, harmful gasses or electrical fields.

Storage conditions:

- Temperature
  - Min. +8 °C
  - Max. +45 °C
- Humidity
  - Min. 25 %
  - Max. 75 %
  - No condensation is allowed under any condition
- Light intensity
  - No direct sunlight

### 2.2 Shelf life

The shelf life for packed products is 4 years after the date code.

## 3. Product handling

### 3.1 ESD protection

Apply the usual ESD protection measures.

### 3.2 Forces on body

Forces on the plastic body during general handling should not exceed 10 N. Apply forces via flat surfaces, parallel to the sensor surface. Avoid stress concentrations at smaller areas.

### 3.3 Forces along leads

Maximum pull force along outer leads is limited to 10 N per lead. Forces in other directions should be prevented as the leads tend to bend easily. Maximum pull force at inner leads is 20 N for all 4 leads combined.

Pushing of leads can cause bulging. As long as bulging is prevented, same push as pull forces are acceptable.

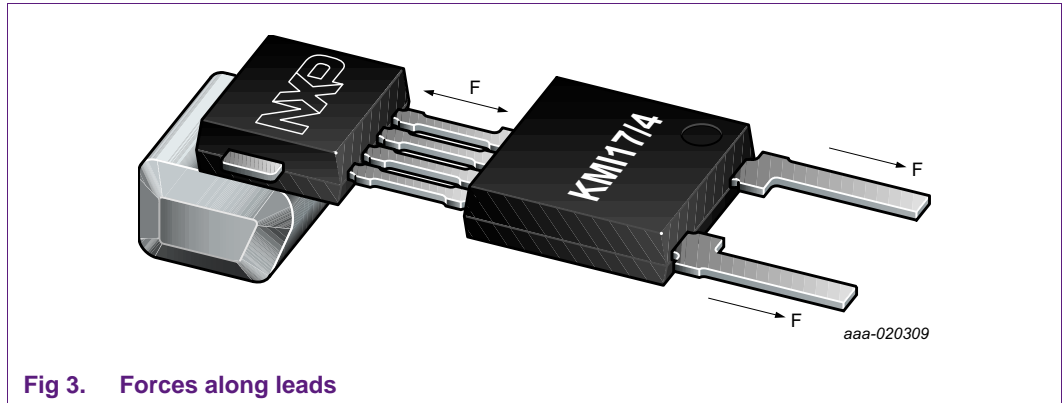


Fig 3. Forces along leads

### 3.4 External magnetic fields

#### 3.4.1 Magnet-to-magnet clearance

During production and transport the (partly) assembled sensors may come close to each other. To prevent magnetization changes of the neighbor products, a minimum clearance is required in any direction. Their magnets should not touch each other. The recommended minimum distance of devices for safe handling is not related to the overmolding material. The magnet-to-magnet clearance depends on the temperature due to the physical parameters of the ferrite material.

- Temperatures above 10 °C (typical temperatures at assembly sites)
  - No special requirement
- Temperatures –40 °C to +10 °C
  - Minimum clearance of 2 mm in case the magnetization of the neighboring devices are perpendicular within  $\pm 30^\circ$  to each other; see [Figure 4](#)
  - Minimum clearance of 2 mm in case of antiparallel magnetization of the neighboring devices for magnetized encoders; see [Figure 5](#)
  - Minimum clearance of 1.5 mm for all other directions (already achieved by typical overmold layers); see [Figure 6](#)

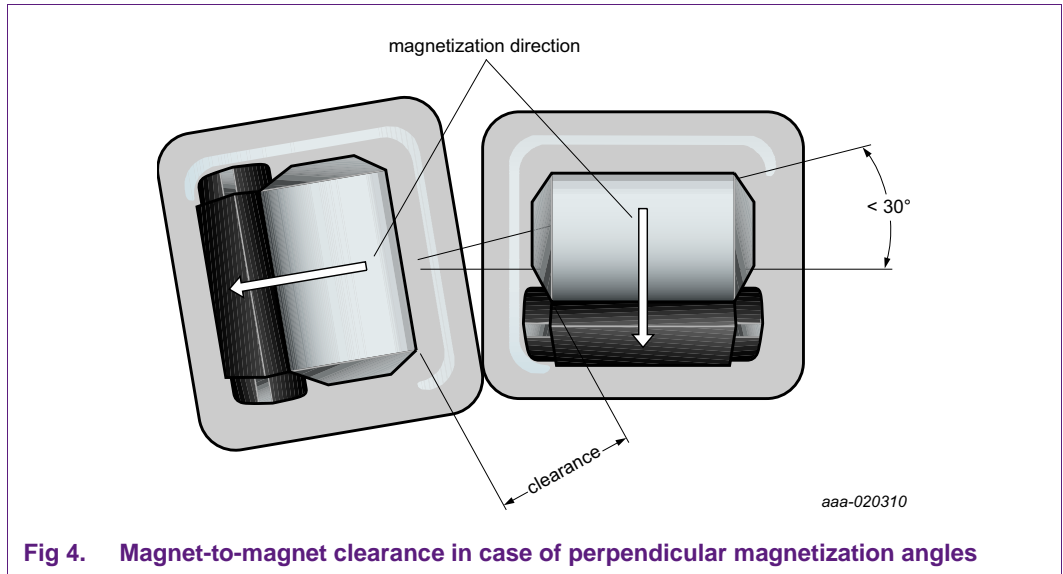


Fig 4. Magnet-to-magnet clearance in case of perpendicular magnetization angles

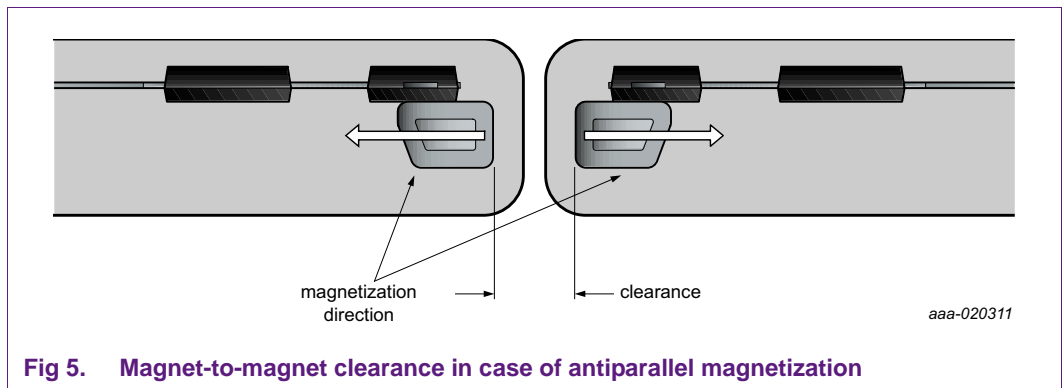


Fig 5. Magnet-to-magnet clearance in case of antiparallel magnetization

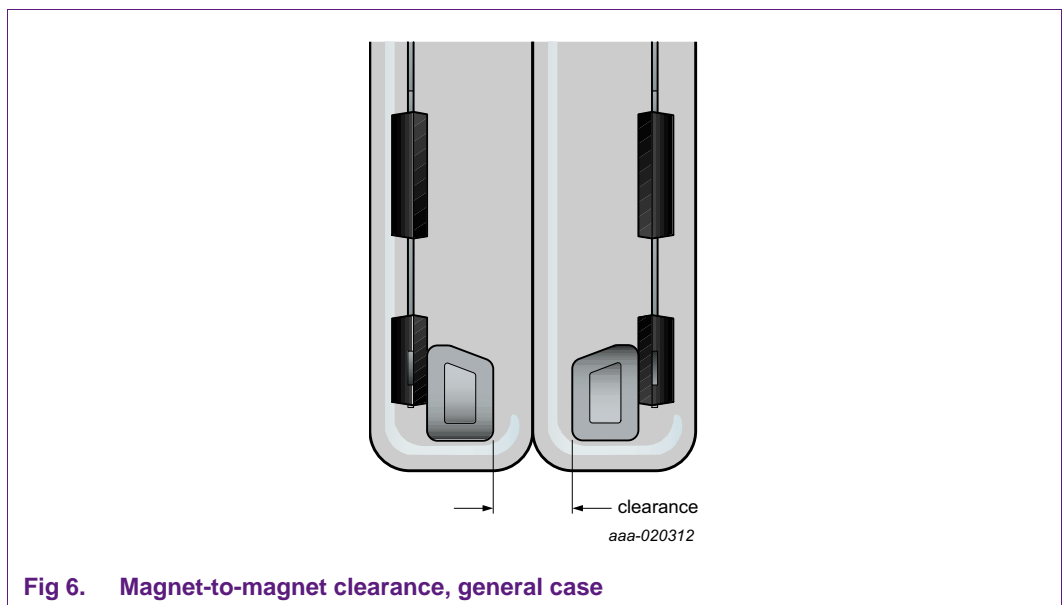


Fig 6. Magnet-to-magnet clearance, general case

**3.4.2 External magnetic field limits**

External magnetic fields should not exceed 37.5 mT (30 kA/m) below 10 °C and 63 mT (50 kA/m) above 10 °C at the bias magnet. The limit is set to prevent magnetization change. It includes short pulses e.g. during welding of the sensor IC leads.

**4. Product assembly**

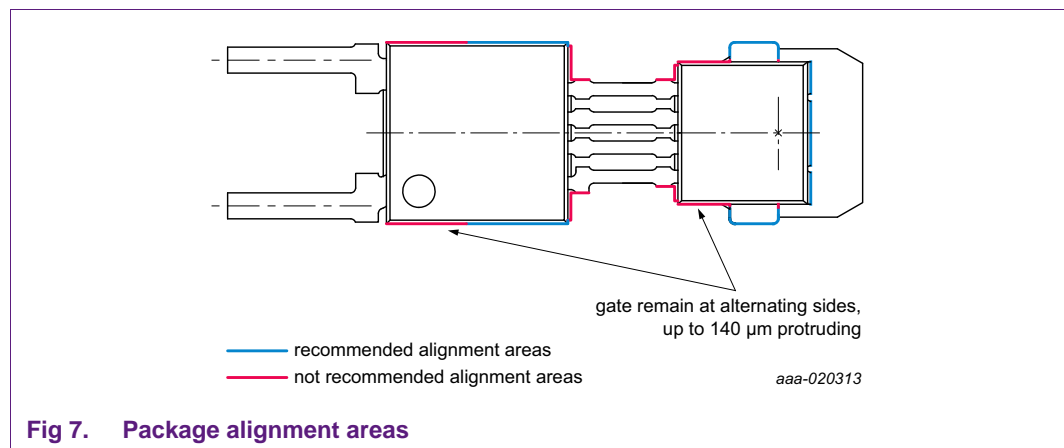
**4.1 Product alignment**

**4.1.1 Package features for alignment**

Blue areas are preferred for alignment in socket.

Red areas should not be used for alignment due to uncontrolled package outline caused by gate remains or potential mold compound flash.

Other areas can be used for alignment.



**Fig 7. Package alignment areas**

**4.1.2 Reading point alignment**

Best reference for the Reading Point (RP) is the Lead Frame (LF) as the die is attached to the LF.

- As the ears are part of the lead frame, they are the preferred alignment feature.
- The RP has a tolerance of ±0.1 mm regarding the ears.
- The lead frame formed the rim (mold compound flowed to the lead frame edge, forming the rim). Therefore, it has the same tolerance of ±0.1 mm.

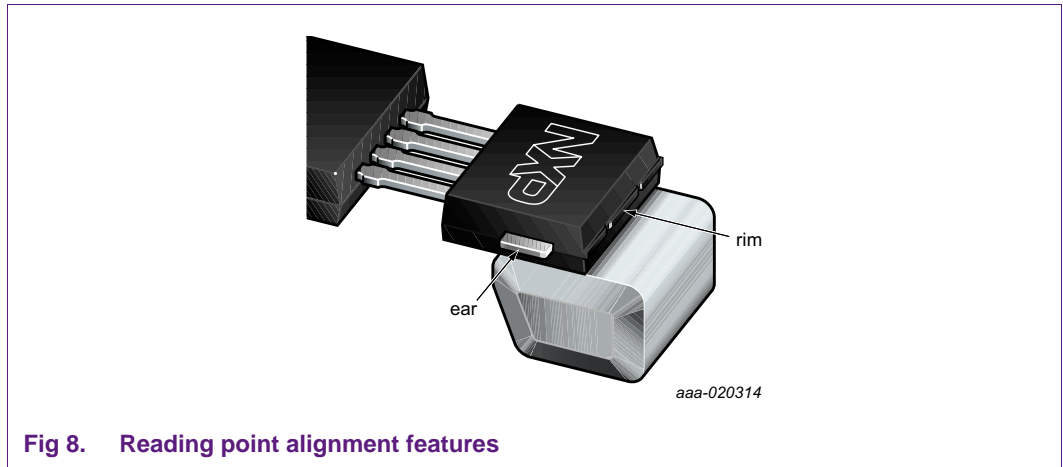


Fig 8. Reading point alignment features

### 4.1.3 Pin alignment

Just aligning the package at the sensor head may not be sufficient to ensure proper positioning of the pins to their external counterparts.

Align the product at the lower body beside the gate position.

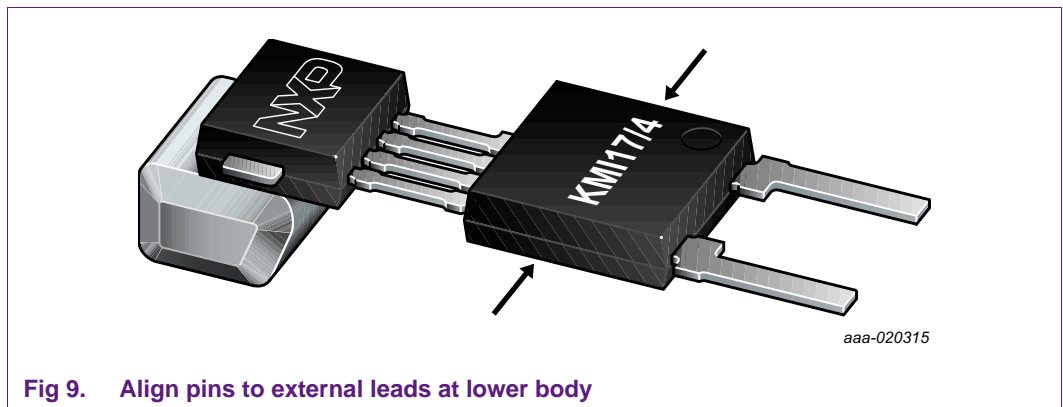


Fig 9. Align pins to external leads at lower body

## 4.2 Lead bending

### 4.2.1 General lead bending information

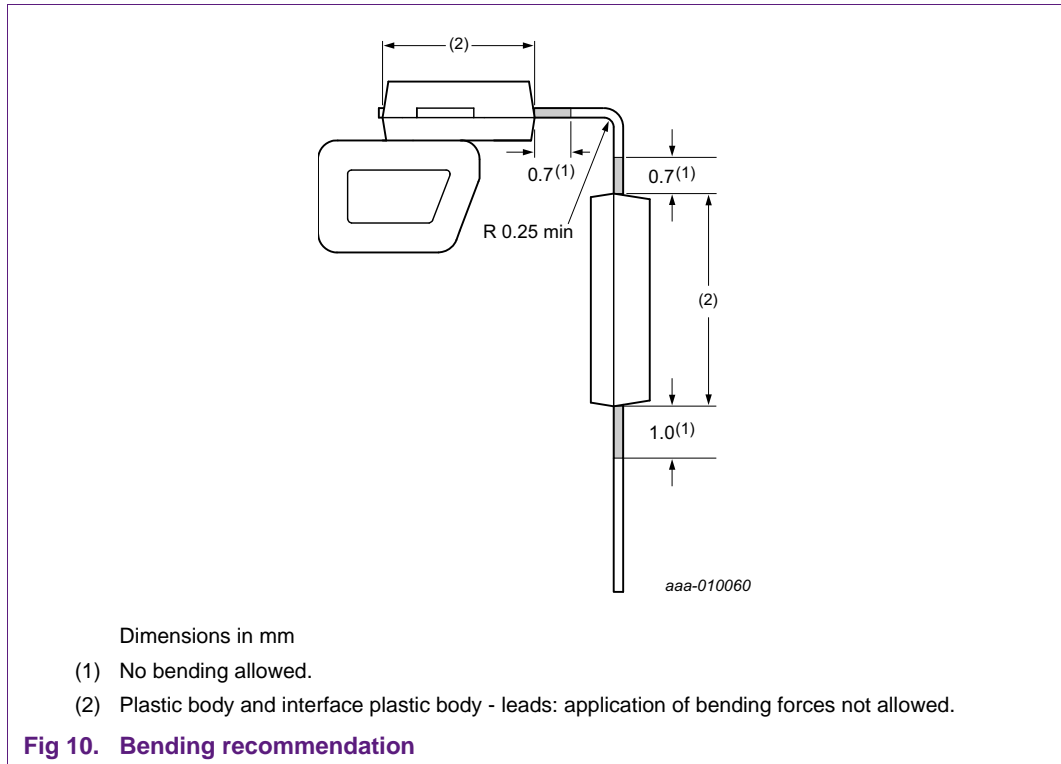
To adapt the packages to customer requirements, the leads can be bent as shown in [Figure 10](#).

The bending operation should not cause gaps in between leads and plastic body at plastic body entrance.

Best bending results are achieved when bending is done at the straight part of the leads.

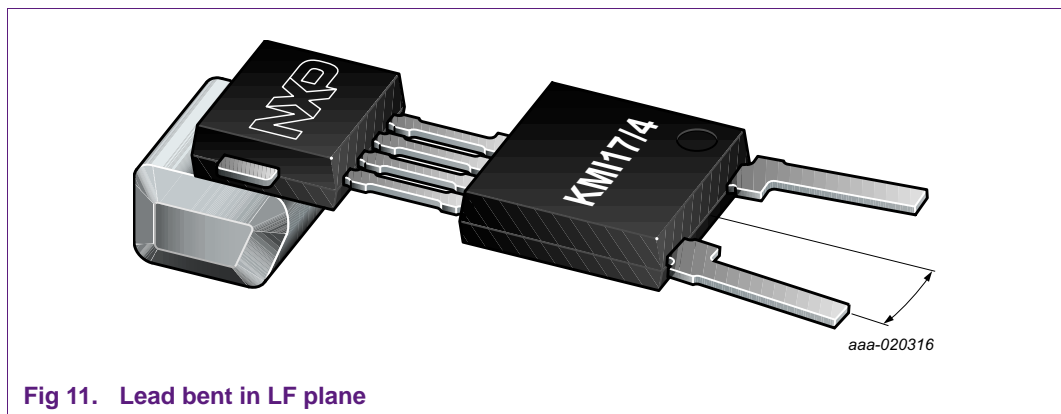
During bending process, pull force should not exceed 10 N per lead (external leads) or cumulative 20 N at internal leads.





**4.2.2 Unintended lead bending in lead frame plane**

Unintended lead bending in lead frame plane should be prevented as it pre-stresses the product, especially the plastic body entrance of the lead. It could damage the lead to plastic body interface and could cause overstress problems in combination with other stress from the assembly steps.



**4.2.3 Unintended lead twist**

Unintended lead twist should be prevented as it pre-stresses the product, especially it could damage the lead to plastic body interface. It could cause overstress problems in combination with other stress from the assembly steps.

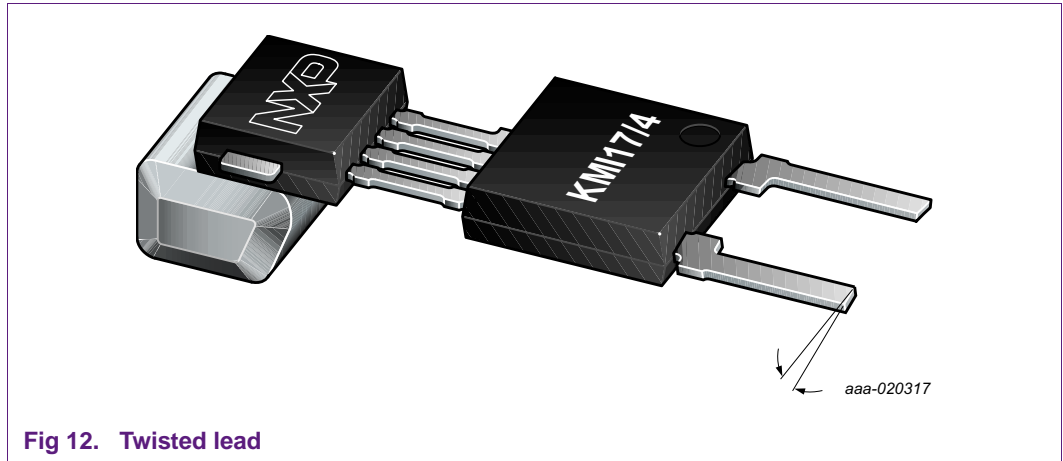


Fig 12. Twisted lead

**4.2.4 Lead bend control**

After intentional or unintentional lead bending or twisting, verify that the products are not mechanically damaged.

**4.2.4.1 Bending zone**

Smooth bending without buckling in bending zone, inner radius > 250 µm.

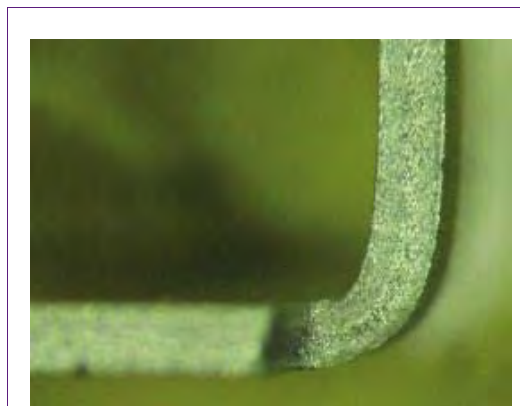


Fig 13. Smooth bending with inner radius > 250 µm, pass



Fig 14. Kink in bending zone, reject

4.2.4.2 Dambar zone

No lead deformation allowed at dambar zone in between bending zone and plastic body.

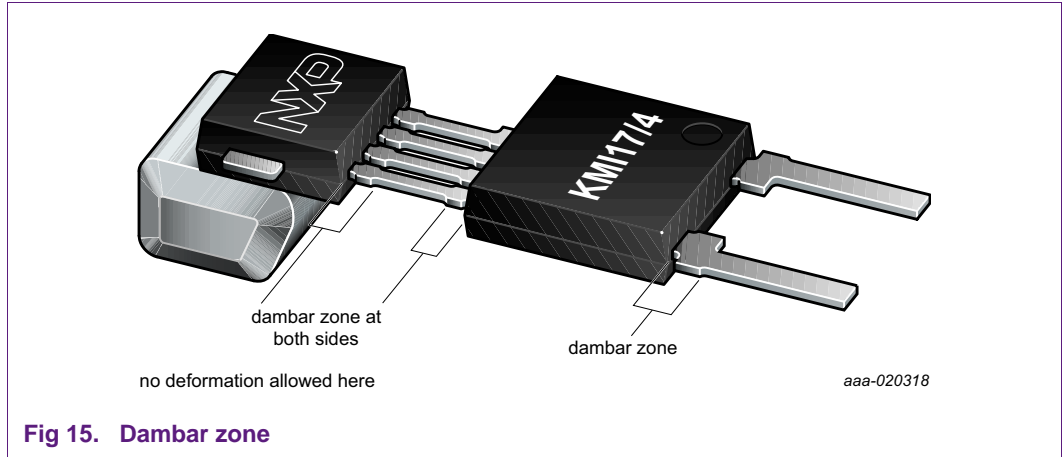


Fig 15. Dambar zone

4.2.4.3 Lead entrance

No gaps are allowed in between leads and plastic body all around internal and external leads.

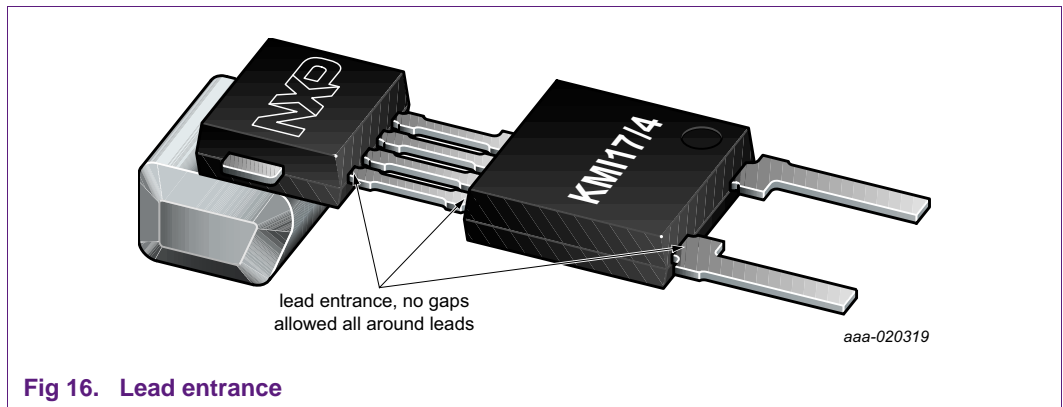


Fig 16. Lead entrance

4.2.4.4 Plating

No exposed copper allowed caused by bending process.

4.3 Molding

Both packages SOT453 and SOT477 are designed for PolyAmide (PA) overmolding. The challenge is the high temperature in combination with high pressure as well as the shear force at the magnet adhesive.

Limiting values are:

- Isostatic pressure to the package
  - 48 MPa
- Sensor IC temperature
  - 250 °C

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